

Powermatic 3520B lathe

VFD-S Inverter

Delta VFD015S21U

Identity Code of AC Drive	Read only
Rated Current Display	Read only
Parameter Reset	d0
Start-up Display Selection	d0
User-Defined Unit	d0
User-Defined Coefficient K	d1.0
Software Version	Read only
Password Input	
Password Decode	
Maximum Output Freq.	d134.0
Maximum Voltage Frequency (Base Freq)	d60.0
Maximum Output Voltage	d230
Mid-Point Frequency	d5.0
Mid-Point Voltage	d20.0
Minimum Output Frequency	d5.0
Minimum Output Voltage	d20.0
Upper Bound of freq.	d100
Lower Bound of freq	d0
Acceleration Time 1 (T _{acc1})	d5.0
Deceleration Time 1 (T _{dec1})	d5.0
Acceleration Time 2	d10.0
Deceleration Time 2	d10.0
Jog Acceleration / Deceleration Time	d10.0
Jog Frequency	d6.0
Auto Acceleration / Deceleration	d0
S-Curve in Acceleration	d0
S-Curve in Deceleration	d0
Jog Decelerating Time	d0.0
Source of Frequency Command	d01
Source of Operation Command	d02
Stop Method	d0
PWM Carrier Frequency	d10
Reverse Operation	d0
Loss of ACI Signal	d0
Analog Auxiliary Frequency Operation	d0
Analog Output Signal	d0
Analog Output Gain	d100
Desired Freq. Attained	d1.0
Terminal Count Value	d0
Preliminary Count Value	d0
Multi-Function Output1 (Photocoupler Output)	d1
Multi-Function Output2 (Relay Output)	d8

Potentiometer Bias Frequency	d0.0
Potentiometer Bias Polarity	d0.0
Potentiometer Frequency Gain	d100
Potentiometer Reverse Motion Enable	d0.0
Multi-Function Input Terminal 1 (M0, M1)	d01
Multi-Function Input Terminal 2 (M2)	d6
Multi-Function Input Terminal 3 (M3)	d7
Multi-Function Input Terminal 4 (M4)	d8
Multi-Function Input Terminal 5(M5)	d9
Line Start Lockout	d1
Up/down frequency Command mode	d3
Acceleration /Deceleration speed of constant up/down frequency	d1
1st Step Speed Freq.	d0.0
2nd Step Speed Freq.	d0.0
3rd Step Speed Freq.	d0.0
4th Step Speed Freq.	d0.0
5th Step Speed Freq.	d0.0
6th Step Speed Freq.	d0.0
7th Step Speed Freq.	d0.0
PLC Mode	d0
PLC Forward/ Reverse Motion	d0
Time Duration Step 0	d0
Time Duration Step 1	d0
Time Duration Step 2	d0
Time Duration Step 3	d0
Time Duration Step 4	d0
Time Duration Step 5	d0
Time Duration Step 6	d0
Time Duration Step 7	d0
Over-Voltage Stall Prevention	d00
Over-Voltage Prevention Level	d390
Over-Current Stall Prevention Level	d130
Over-Torque Detection Mode	d0
Over-Torque Detection Level	d150
Time setting for Over-torque Detection	d0.1
Electronic Thermal Overload Relay Selection	d2
Electronic Thermal Characteris	d60
Motor Rated Current	d120
Motor No-Load Current	d50
Torque Compensation	d01
Slip Compensation	d0.0
DC Braking Voltage Level	d0
DC Braking Time during Start-Up	d0.0
DC Braking time during Stopping	d0.0
Start-Point for DC Braking	d0.0
Momentary Power Loss Operation Selection	d0
Maximum Allowable Power Loss Time	d2.0

B.B. Time for Speed Search	d0.5
Maximum Speed Search Current Level	d150
Skip Frequency 1 Upper Bound	d0.0
Skip Frequency 1 Lower Bound	d0.0
Skip Frequency 2 Upper Bound	d0.0
Skip Frequency 2 Lower bound	d0.0
Skip Frequency 3 Upper bound	d0.0
Skip Frequency 3 Lower Bound	d0.0
Auto Restart After Fault	d0
VR Functio	d2
Dynamic Braking Voltage	d380
DC Braking Lower Bound Limit	d0.0
Communication Address	d1
Transmission Speed	d1
Transmission Fault Treatment	d0
Modbus Communication Watchdog Timer	d0
Communication Protocol	d0
PID Feedback Terminal Selection	d0
Feedback Signal Gain	d100
Proportional Gain (P)	d100
Integral Time (I)	d100
Differential Time (D)	d0
Integration's Upper Bound Frequency	d100
One-Time Delay	d0
PID Frequency Output Command Limit	d100
Detection Time of the Feedback Error	d0.0
Feedback Signal Fault Treatment	d0
Dwell (sleep) Frequency	d0.0
Revival Frequency	d0.0
Dwell (sleep) Period	d0.0
PID User Defined	d0.0